



# Linear Regression

Notes from ISLR book

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## 1. Model

### 1.1 Principles

The goal is to find an estimate  $\hat{y}$  of the variable  $y$  with a linear combination of  $p$  predictors  $x_1, \dots, x_p$

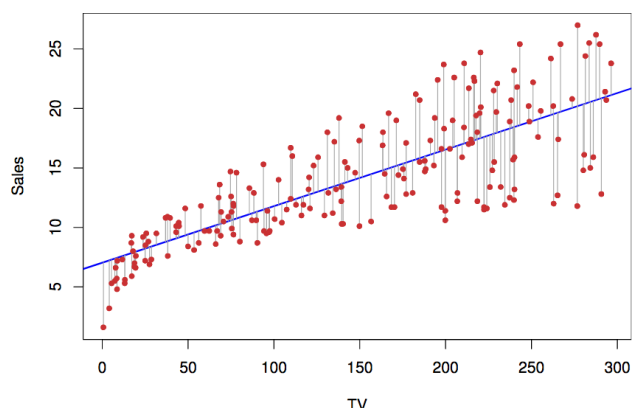
$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x_1 + \dots + \hat{\beta}_p x_p \quad (1)$$

The estimation of the intercept  $\hat{\beta}_0$  and the slopes  $\hat{\beta}_{1..p}$  is done by the least square method which minimises the **Residual Sum of Squares** (RSS)

$$RSS = \sum_{i=1}^n [y_i - \underbrace{(\hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \dots + \hat{\beta}_p x_{ip})}_{\hat{y}_i}]^2 \quad (2)$$

The average of the RSS calculated over the  $n$  points is called the **Mean Squared Error** (MSE)

$$MSE = \frac{RSS}{n} \quad (3)$$



**Figure 1.** Linear regression fit ( $p = 1$ ),  $y$ =Sales and  $x_1$ =TV

The presence of a random noise term  $\epsilon$  in the true relationship between  $x$  and  $y$  variables implies

that the true population mean  $\mu$  can only be approximated by the sample mean  $\bar{y} = \hat{\mu}$ . Assuming that the observations are uncorrelated, the standard error of  $\hat{\mu}$  is calculated from the variance of the noise parameter  $Var(\epsilon) = \sigma^2$  which gives  $SE(\hat{\mu}) = \sigma^2/n$ .

Most of the time  $\sigma$  is not known, but we can estimate it with the **Residual Standard Error** (RSE)

$$RSE = \sqrt{\frac{RSS}{(n-p-1)}} \sim \sigma \quad (4)$$

This estimate of  $\sigma$  is also used to calculate the standard errors on the parameters  $SE(\hat{\beta}_j)$ <sup>1</sup>. Those errors are needed to get the **confidence intervals**  $\hat{\beta}_j \pm \alpha \cdot SE(\hat{\beta}_j)$  which measure the uncertainty on coefficients<sup>2</sup>. Not to be mistaken with the **prediction interval** that quantifies the expectation on the value of a data point (ie error bands).

### 1.2 Response-predictor relationship

To test for a relationship between the response and the  $p$  predictors, we have 2 choices:

- **t-statistic** to test how far from 0 each  $\hat{\beta}_j$  are, in terms of standard errors

$$t = \frac{\hat{\beta}_j - 0}{SE(\hat{\beta}_j)} \quad (6)$$

The **p-value** is the probability of finding a value equal or bigger than  $|t|$ . It is calculated by integrating the t-distribution with  $n - 2$  degrees of freedom from  $|t|$  to  $\infty$  as in Figure 2 (left). The smaller it is, the less likely we are to find a  $\hat{\beta}_j$  that far from 0, therefore the higher the chance of a relationship between the response and the  $j$ th predictor.

Note however there is always a 5% chance of observing a p-value below 0.05.

- **F-statistic** to test that at least one predictor in a subset  $q$  of  $p$  predictors is linked to the response, ie at least one of the  $\hat{\beta}_q$  is non-null, where  $q \in [1, p]$ .

$$F = \frac{(RSS_0 - RSS)/q}{RSS/(n-p-1)} \quad (7)$$

<sup>1</sup>In the case where  $p = 1$ , it gives

$$SE(\hat{\beta}_0)^2 = \sigma^2 \left[ \frac{1}{n} + \frac{\bar{x}^2}{\sum_{i=1}^n (x_i - \bar{x})^2} \right], SE(\hat{\beta}_1)^2 = \frac{\sigma^2}{\sum_{i=1}^n (x_i - \bar{x})^2} \quad (5)$$

<sup>2</sup>For the 95% confidence interval,  $\alpha$  is the 97.5% quantile of the t-distribution with  $n - 2$  degrees of freedom (the t-distribution converges toward a gaussian as  $n$  increases).

where  $RSS_0$  is the  $RSS$  of the model where only the  $p - q$  predictors are used<sup>3</sup>.

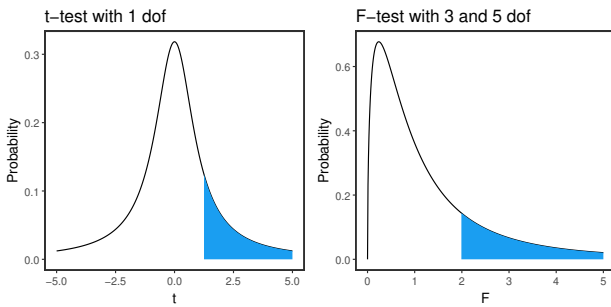


Figure 2. Example of t (left) and F (right) statistics.

### 1.3 Miscellaneous

**Categorical predictors** When a predictor is qualitative, a baseline is defined by default. In the absence of interaction terms with categorical predictors, the category effect is independent of other predictor values.

**Additive assumption** The effect of a change in  $x_i$  on  $y$  is independent of other predictors. Adding interaction terms will break this assumption.

**Hierarchical principle** Always include the main effects of the predictors that are involved in interaction terms, even if their p-values is big.

**Linear assumption** A change of  $y$  due to one unit change in  $x_i$  is constant regardless of the value of  $x_i$ . Adding polynomial terms will break that assumption.

## 2. Diagnostics

### 2.1 $R^2$ measure

A first measure of the model accuracy in the RSE. It measures the lack of fit of the model to the data but is expressed in measure of  $y$  therefore is not general to every datasets. A better metric is the  $R^2$  test

$$R^2 = 1 - \frac{RSS}{TSS} \tag{8}$$

**TSS** is the total sum of squares  $TSS = Var(y) = \sum_{i=1}^n (y_i - \bar{y})^2$ . It represents the total amount of variance in the response previous to the fit.

**RSS** is the amount of variance that is left unexplained once the fit is performed.

$R^2$  represents the proportion of variance explained by the fit. The closer to 1, the better the fit !

<sup>3</sup>See this [tool](#) for a live p-value calculation demo with t and F distributions.

### 2.2 Residual plot

Using a linear model implies that your data seems linear. A good way of checking this is by plotting the residuals vs the fitted values: it should be constantly centred around 0 like in the right top right panel of Figure 3. This residual plot also allows to check for non-constant variance of the error terms, or **heteroscedasticity**, by looking for a funnel shape. This is important to ensure that  $\sigma^2 = Var(\epsilon)$  is constant since the calculation of confidence intervals and errors rely upon it. Taking the log of the response or, if the response is an average over  $n_i$  values, using a weighted mean instead could help ( $\sigma_i^2 = \sigma^2/n_i$ ), see bottom panels of Figure 3

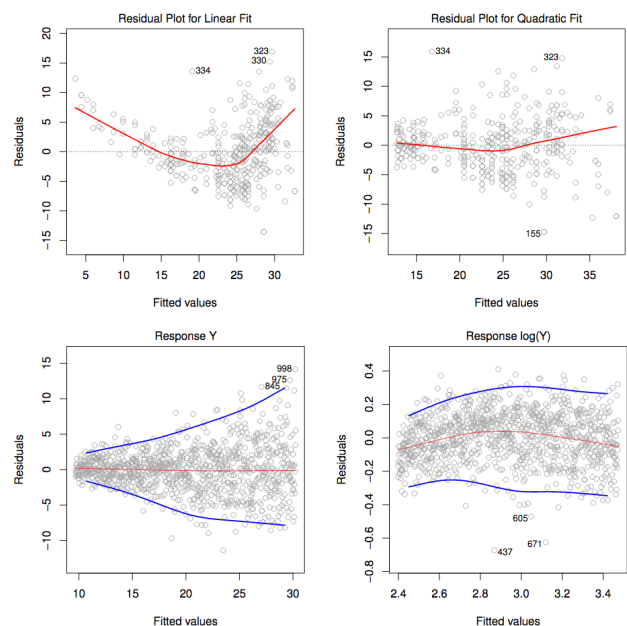


Figure 3. Top: Residuals vs fitted values for linear (top left) and quadratic (top right) regression. Bottom: illustration of heteroscedasticity.

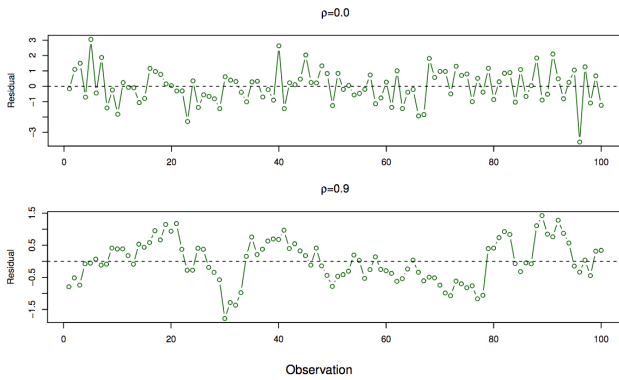
### 2.3 Tracking

$SE(\hat{\beta}_j)$  are calculated assuming **uncorrelated errors**. If there is correlation,  $SE(\hat{\beta}_j)$ , and therefore the confidence intervals, will be underestimated. Imagine all data is duplicated, we have a sample of size  $2n$  instead of  $n$ , same predictions but confidence interval will be narrower by a factor  $\sqrt{2}$ . Such correlations often occur in time series, check for **tracking** in the residuals as in Figure 4.

### 2.4 Outliers and High-leverage

- **High-leverage**: observation with an unusual  $x_i$ . This impact a lot the regression fit. These points are identified with the leverage statistic:

$$h_i = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{\sum_{i=1}^n (x_i - \bar{x})^2} \tag{9}$$



**Figure 4.** Top: no tracking (small correlations), Bottom: tracking (high correlations)

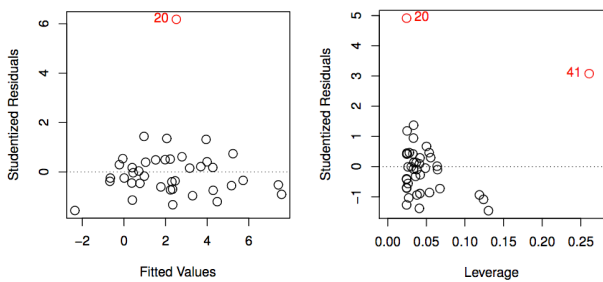
- **Outliers:** observation for which  $y_i$  is far from  $\hat{y}_i$  given  $x_i$ . Outliers tend to increase RSE, hence  $SE(\hat{\beta})$  and p-values. To determine these points several measures are possible such as the **studentized residuals**<sup>4</sup>:

$$t_i = \frac{y_i - \hat{y}_{(-i)}}{\sqrt{MSE_{(-i)}(1 - h_i)}} \quad (10)$$

where the index  $(-i)$  denote the value for the  $i$ th point calculated from a model where it was removed.

Both outliers and high-leverage can be spotted with the **Cook's distance** which measures how much all of the fitted values change when the  $i$ th observation is removed.

$$D_i = \frac{\sum_{i'=1}^n (\hat{y}_{i'} - \hat{y}_{i',(-i)})^2}{p \cdot MSE} = \frac{(y_i - \hat{y}_i)^2}{p \cdot MSE} \left[ \frac{h_i}{(1 - h_i)^2} \right] \quad (11)$$



**Figure 5.** Studentized res.(left) and leverage (right)

### 2.5 Collinearity

If two predictors are collinear, it will be hard to distinguish their individual effects. This will increase the standard errors of their coefficients  $SE(\hat{\beta}_j)$  and lead to a poor t-test. To detect direct collinearity, one can just look at the **correlation matrix** between all predictors.

$$Cor(X, Y) = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}} \quad (12)$$

<sup>4</sup>NB: Studentized residuals do not consider the  $i^{th}$  point while the standardized residuals do use the full dataset.

However, in the case of multicollinearity, it's better to look at the **variance inflation factor**:

$$VIF = \frac{1}{1 - R_{X_j|X_{-j}}^2} \quad (13)$$

where  $R_{X_j|X_{-j}}^2$  is the  $R^2$  of a regression of  $X_j$  onto all the other predictors. It is equivalent to the variance of  $\hat{\beta}_j$  calculated with a model containing all the predictors divided by the variance of  $\hat{\beta}_j$  in a model with only  $X_j$ .  $R_{X_j|X_{-j}}^2$  close to one means  $VIF$  high and presence of collinearity.

## 3. KNN Regression

If not sure about the linearity of the data, it is possible to use a non-parametric regression approach,

$$\hat{f}(x_0) = \frac{1}{K} \sum_{x_i \in \mathcal{N}_0} y_i \quad (14)$$

This could work better than linear regression if the number of predictors remain low (curse of dimensionality).